

Basic Fail-Safe modulating actuator for controlling dampers in typical commercial **HVAC applications.** 

- Torque motor 35 in-lb [4 Nm]
- Nominal voltage AC/DC 24 V
- Control Modulating
- Position feedback 2...10 V







LF24-SR US

5-year warranty





| Tec | hnical | data |
|-----|--------|------|
|     |        |      |

| El€ | ectric | al da | ata |
|-----|--------|-------|-----|

| Nominal voltage                    | AC/DC 24 V   |
|------------------------------------|--|
| Nominal voltage frequency          | 50/60 Hz   |
| Nominal voltage range              | AC 19.228.8 V / DC 21.628.8 V                            |
| Power consumption in operation     | 2.5 W  |
| Power consumption in rest position | 1 W  |
| Transformer sizing                 | 5 VA   |
| Electrical Connection              | 18 GA plenum cable, 1 m, with 1/2" NPT conduit connector |
| Overload Protection                | electronic throughout 095° rotation                      |
| Electrical Protection              | actuators are double insulated                           |

# **Functional data**

| Torque motor                  | 35 in-lb [4 Nm]  |
|-------------------------------|--|
| Operating range Y             | 210 V  |
| Operating range Y note        | 420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)                   |
| Input impedance               | 100 k $\Omega$ for 210 V (0.1 mA), 500 $\Omega$ for 420 mA |
| Position feedback U           | 210 V  |
| Position feedback U note      | Max. 0.7 mA  |
| Direction of motion motor     | selectable with switch 0/1                                 |
| Direction of motion fail-safe | reversible with cw/ccw mounting                            |
| Angle of rotation             | Max. 95°   |
| Running Time (Motor)          | 150 s / 90°  |
| Running time motor note       | constant, independent of load                              |
| Running time fail-safe        | <25 s @ -4122°F [-2050°C], <60 s @ -22°F<br>[-30°C]        |
| Noise level, motor            | 30 dB(A)   |
| Noise level, fail-safe        | 62 dB(A)   |
| Position indication           | Mechanical   |
| Power source UL               | Class 2 Supply   |
| Degree of protection IEC/EN   | IP54   |

# Safety data

| Power source UL              | Class 2 Supply  |
|------------------------------|---|
| Degree of protection IEC/EN  | IP54  |
| Degree of protection NEMA/UL | NEMA 2  |
| Enclosure                    | UL Enclosure Type 2   |
| Agency Listing               | cULus acc. To UL 873 and CAN/CSA C22.2 No. 24-93  |
| Quality Standard             | ISO 9001  |
| UL 2043 Compliant            | Suitable for use in air plenums per Section<br>300.22(C) of the NEC and Section 602 of the<br>IMC |
| Ambient humidity             | Max. 95% RH, non-condensing   |
| Ambient temperature          | -22122°F [-3050°C]  |
| Storage temperature          | -40176°F [-4080°C]  |
| Servicing                    | maintenance-free  |
|                              |   |



Weight Weight 3.4 lb [1.6 kg]

Materials Housing material galvanized steel

Footnotes †Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

#### **Product features**

### **Application**

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft from 3/8" up to 1/2" in diameter by means of its universal clamp, 1/2" shaft centered at delivery. For shafts up to 3/4" use K6-1 accessory. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a 2...10 V, or with the addition of a  $500\Omega$  resistor, a 4...20 mA control input from an electronic controller or positioner. A 2...10 V feedback signal is provided for position indication.

#### Operation

The LF series actuators provide true spring return operation for reliable fail-safe application and positive close-off on air tight dampers. The spring return system provides consistent torque to the damper with, and without, power applied to the actuator. The LF series provides 95° of rotation and is provided with a graduated position indicator showing 0 to 95°. The LF24-SR US uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. Power consumption is reduced in holding mode.

#### Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 3/4" diameter and center on a 1/2" shaft (default). Actuator shall deliver a minimum output torque of 35 in-lbs. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 feedback signal shall be provided for position feedback. The actuator must be designed so that they may be used for either clockwise or counter clockwise failsafe operation. Actuators shall be cULus listed, have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

#### **Accessories**

| _         | _             |
|-----------|---------------|
| Flactrica | l accessories |
|           |               |

| Description   | Туре    |
|---|---------|
| DC Voltage Input Rescaling Module                                 | IRM-100 |
| Auxiliary switch, mercury-free                                    | P475    |
| Auxiliary switch, mercury-free                                    | P475-1  |
| Signal simulator, Power supply AC 120 V                           | PS-100  |
| Convert Pulse Width Modulated Signal to a 210 V Signal for Belimo | PTA-250 |
| Proportional Actuators  |         |
| Positioner for wall mounting                                      | SGA24   |
| Positioner for front-panel mounting                               | SGF24   |
| Resistor, 500 $\Omega$ , 1/4" wire resistor with 6" pigtail wires | ZG-R01  |
| Resistor kit, 50% voltage divider                                 | ZG-R02  |
| Transformer, AC 120 V to AC 24 V, 40 VA                           | ZG-X40  |



#### Technical data sheet LF24-SR US

#### Mechanical accessories

| Description  | Туре          |
|--|---------------|
| Shaft extension 170 mm ø10 mm for damper shaft ø616 mm                     | AV6-20        |
| End stop indicator   | IND-LF        |
| Shaft clamp  | K6 US         |
| for LF   |               |
| Shaft clamp reversible, clamping range ø1620 mm                            | K6-1          |
| Ball joint suitable for damper crank arm KH8 / KH10                        | KG10A         |
| Ball joint suitable for damper crank arm KH8                               | KG6           |
| Ball joint suitable for damper crank arm KH8                               | KG8           |
| Damper crank arm Slot width 8.2 mm, for ø1.05"                             | KH12          |
| Damper crank arm Slot width 6.2 mm, clamping range ø1018 mm                | KH6           |
| Damper crank arm Slot width 8.2 mm, clamping range ø1018 mm                | KH8           |
| Actuator arm, clamping range ø816 mm, Slot width 8.2 mm                    | KH-LF         |
| V-bolt Kit for KH-LF.  | KH-LFV        |
| Anti-rotation bracket LF.  | LF-P          |
| Push rod for KG10A ball joint 36" L, 3/8" diameter                         | SH10          |
| Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).                | SH8           |
| Wrench 0.32 in and 0.39 in [8 mm and 10 mm]                                | TOOL-06       |
| Angle of rotation limiter, with end stop                                   | ZDB-LF        |
| Form fit adapter 8x8 mm  | ZF8-LF        |
| Mounting bracket   | ZG-109        |
| Linkage kit  | ZG-110        |
| Mounting bracket   | ZG-112        |
| for LF   |               |
| Damper clip for damper blade, 3.5" width.                                  | ZG-DC1        |
| Damper clip for damper blade, 6" width.                                    | ZG-DC2        |
| LF crankarm adaptor kit (includes ZG-112).                                 | ZG-LF112      |
| LF crankarm adaptor kit (T bracket included).                              | ZG-LF2        |
| Shaft extension for 3/8" diameter shafts (4" L).                           | ZG-LMSA-1     |
| Shaft extension for 1/2" diameter shafts (5" L).                           | ZG-LMSA-1/2-5 |
| Weather shield 13x8x6" [330x203x152 mm] (LxWxH)                            | ZS-100        |
| Baseplate, for ZS-100  | ZS-101        |
| Weather shield 406x213x102 mm [16x8-3/8x4"] (LxWxH)                        | ZS-150        |
| Explosion proof housing 16x10x6.435" [406x254x164 mm] (LxWxH), UL          | ZS-260        |
| and CSA, Class I, Zone 1&2, Groups B, C, D, (NEMA 7), Class III, Hazardous |               |
| (classified) Locations   |               |
| Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA          | ZS-300        |
| 4X, with mounting brackets   |               |
| Weather shield 17-1/4x8-3/4x5-1/2" [438x222x140 mm] (LxWxH), NEMA          | ZS-300-5      |
| 4X, with mounting brackets   |               |
| Shaft extension 1/2"   | ZS-300-C1     |
| Shaft extension 3/4"   | ZS-300-C2     |
| Shaft extension 1"   | ZS-300-C3     |
| Linkage kit  | ZG-JSL        |
| Jackshaft Retrofit Linkage with Belimo Rotary Actuators                    |               |

#### **Electrical installation**



# Marning! Live electrical components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

A Provide overload protection and disconnect as required.

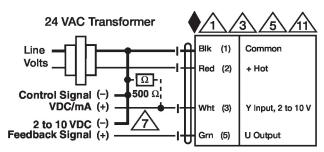
Actuators may also be powered by DC 24 V.

6 Only connect common to negative (-) leg of control circuits.

 $\Lambda$  A 500  $\Omega$  resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.





2...10 V / 4...20 mA Control

## **Dimensions**

